

See discussions, stats, and author profiles for this publication at: <https://www.researchgate.net/publication/268252692>

Lorentzian circle as a Lie group and a C^∞ action on Lorentz spaces of two dimension

Article in *Communications* · January 1999

DOI: 10.1501/Commua1_0000000398

CITATIONS

0

READS

24

2 authors:



Halit Gündoğan

Kirikkale University

22 PUBLICATIONS 91 CITATIONS

SEE PROFILE



Bulent Karakas

Yuzuncu Yil University

25 PUBLICATIONS 16 CITATIONS

SEE PROFILE

Some of the authors of this publication are also working on these related projects:



bulentkarakas@gmail.com [View project](#)



Dual Split Quaternions and Screw Motion in 3-Dimensional Lorentzian Space [View project](#)

LORENTZIAN CIRCLE AS A LIE GROUP AND A C^∞ ACTION ON LORENTZ SPACES OF TWO DIMENSION

H. GÜNDOĞAN* and B. KARAKAŞ**

**Department of Mathematics, University of Kırıkkale, Kırıkkale-Turkey*

***Department of Mathematics, University of Yüzüncü Yıl, Van-Turkey*

ABSTRACT

We define a product on Lorentz circle that is similar to Lorentzian inner product. This product is expanded to Lorentz space of two dimension. So we have an C^∞ action of Lorentz circle on Lorentz space of two dimension. It is noted that this action provides some isometrics of L^2 .

1. INTRODUCTION

A Lie group G is a group which has the structure of a differentiable manifold and for which the group function

$$\circlearrowleft : G \times G \longrightarrow G$$

defined by $\circlearrowleft(g_1, g_2) = g_1 g_2$ is differentiable. Given an element a of a Lie group G , the function $L : G \rightarrow G$ defined $g \rightarrow ag$ is called left translation. A Lie group G is said to act on a differentiable manifold M as Lie transformation group if we are given a global surjection

$$\phi : G \times M \rightarrow M$$

which is differentiable such that if $g, h \in G$ and $m \in M$

$$\phi(g, \phi(h, m)) = \phi(gh, m)$$

G is said act transitively on M if, given any two points $m_1, m_2 \in M$ there is an element $g \in G$ such that $m_2 = gm_1$.

By a transformation of a manifold M , we mean a diffeomorphism of M onto itself. A group G is said to act on M as a transformation group. If there is a global function

$$\phi : G \times M \rightarrow M$$

such that

- i) the function ϕ_g , defined for any given $g \in G$ by $m \rightarrow \phi(g, m)$ is a transformation of M ,
- ii) if $g, h \in G$, $\phi_g \circ \phi_h = \phi_{gh}$.

Suppose that e is the unit element of G , then ϕ_e is the identity element on M , for if $m \in M$ and $m' = (\phi_e - 1)_m$. The group is said to act effectively on M if e is the only element of G such that $\phi_g m = m$ for all $m \in M$. It is said to act freely on M if e is the only element of G such that $\phi_g m = m$ for some M .

A transformation group G acting on a manifold M sets up an equivalence relation on M . The equivalence class containing a point m is the range of the function $\phi_m : G \rightarrow M$ and we call it the orbit of m [1].

We will denote Lorentzian circle on L^2 by L_1^1 . In this study, it was shown that L_1^1 is a Lie group with a binary operation defined on L^1 as hypercylindrical product defined by [3]. A C^∞ -action on L^2 of this Lie group is defined and some properties of it were given. Finally, with the help of this C^∞ -action some isometries of L^2 were obtained.

1.1 LORENTZ MANIFOLDS, LORENTZ VECTOR SPACES AND LORENTZ CIRCLE

A metric tensor g on a differentiable manifold M is a symmetric nondegenerate $(0,2)$ tensor field on M of constant index. A semi-Riemannian manifold is a differentiable manifold M furnished with a metric tensor g . Thus a semi-Riemannian manifold is an ordered pair (M, g) .

The common value ν of index g_p on a semi-Riemannian manifold M is called the index of M satisfying $0 \leq \nu \leq n = \dim M$. If $\nu = 0$, M is a Riemannian manifold since each g_p is an (positive definite) inner product on $T_p(M)$. If $\nu = 1$ and $n \leq 2$, M is Lorentz manifold.

In this study, v will take the values 1 and 2, and L^2 will denote a Lorentz manifold of two dimension. So, the metric tensor is defined by

$$\langle X, Y \rangle_L = x_1 y_1 - x_2 y_2$$

or

$$\langle X, Y \rangle_L = \langle X, Y_s \rangle_E$$

where Y_s is symmetry of Y according to the x -axes and $X = (x_1, x_2)$, $Y = (y_1, y_2)$ [4].

2 LIE GROUP STRUCTURE OF L_1^1

We define a binary operation on L_1^1 by

$$\odot : L_1^1 \times L_1^1 \longrightarrow L_1^1$$

$$\odot(X, Y) = (\langle X, Y \rangle_E, \langle X, Y_s \rangle_E)$$

where $\langle \cdot, \cdot \rangle_E$ is Euclidean inner product and Y_s is symmetry of $Y \in \mathbb{R}^2$ according to the straight line $y = x$. We have, the following

Theorem 1. The system (L_1^1, \odot) is a commutative group.

Proof. For all $X, Y \in L_1^1$,

1. $\odot(X, Y) \in L_1^1$,
2. $\odot(X, Y) = (x_1 y_1 + x_2 y_2, x_1 y_2 + x_2 y_1)$
 $= (x_1 y_1 + x_2 y_2, y_1 x_2 + y_2 x_1)$
 $= \odot(Y, X)$

3. $e=(1,0)$ is the identity element

4. The inverse element of $X = (x_1, x_2)$ is $(x_1 - x_2)$.

By Theorem 1, L_1^1 becomes a Lie group since $L_1^1 \subset \mathbb{R}^2$ is a differentiable submanifold, and the symmetry function and the inner product are differentiable functions.

For $r \in \mathbb{R}^+$, we define the set L_r^1 as

$$L_r^1 = \{(x, y) \in L^2 \mid x^2 - y^2 = r^2\}$$

and action $\theta : L_1^1 \times L_r^1 \rightarrow L_r^1$, $\theta((x_1, x_2), (y_1, y_2)) = (x_1 y_1 + x_2 y_2, x_1 y_2 + x_2 y_1)$.

Theorem 2. L_1^1 acts transitively on L_r^1 .

Proof. For $p, q \in L_r^1$ we can define an element $X = (x_1, x_2)$ where

$$x_1 = \frac{\langle p, q \rangle}{r^2} \quad \text{and} \quad x_2 = \frac{\langle p, q_s \rangle}{r^2}.$$

Then, it is clear that $X \in L_1^1$ and

$$\theta(X, Q) = P$$

This completes the proof.

For $X \in L_r^1, (\theta)_x$ the orbit of X under the action θ is L_r^1 .

Theorem 3. L_1^1 acts effectively on L_1^1 .

Proof. We have to show that for all $m \in L_1^1$ the equation $\theta(g, m) = m$ is satisfied only for $g=e$. In fact

$$\theta(g, m) = m \Rightarrow g_1 m_1 + g_2 m_2 = m_1$$

$$g_1 m_2 + g_2 m_1 = m_2$$

$$\Rightarrow g_1 = \frac{\det \begin{bmatrix} m_1 & m_2 \\ m_2 & m_1 \end{bmatrix}}{r^2} = 1$$

$$g_2 = \frac{\det \begin{bmatrix} m_1 & m_1 \\ m_2 & m_2 \end{bmatrix}}{r^2} = 0$$

so $g = e$.

3. THE SET \tilde{L}_r^1

We define the set \tilde{L}_r^1 as

$$\tilde{L}_r^1 = \{(x, y) \mid y^2 - x^2 = r^2\}$$

so we can define an action

$$\bar{O} : \tilde{L}_r^1 \times \tilde{L}_r^1 \longrightarrow \tilde{L}_r^1$$

$$\bar{O}(X, Y) = (\langle X, Y \rangle_E, \langle X, Y_S \rangle_E)$$

In this case, we evidently have;

1. (\tilde{L}_r^1, \bar{O}) is a commutative group
2. \tilde{L}_r^1 is a Lie group

3. \tilde{L}_r^1 acts on \tilde{L}_r^1 as a Lie transformation group with the function $\tilde{\theta}$ defined by $\tilde{\theta}(g, X) = (\langle g, X \rangle_E, \langle g, X_S \rangle_E)$
4. \tilde{L}_r^1 acts transitively on \tilde{L}_r^1
5. \tilde{L}_r^1 acts effectively on \tilde{L}_r^1
6. $(\tilde{\theta})_X = \tilde{L}_r^1$, where $X \in \tilde{L}_r^1$

3.1. AN ACTION ON L^2

For all $X = (x_1, x_2) \in L^2$, we have

$$x_1^2 - x_2^2 = r^2 \quad \text{or} \quad x_2^2 - x_1^2 = r^2$$

where $r \in \mathbf{R}^+ \cup \{0\}$. So, we write

$$\left(\bigcup_r L_r^1\right) \cup \left(\bigcup_r \tilde{L}_r^1\right) \supseteq L^2.$$

Then, we conclude

Theorem 4. L_1^1 acts on L^2 as a Lie transformation group with the function θ' defined by

$$\theta'(X, Y) = \begin{cases} \theta(X, Y), & \text{if } y_1 \geq y_2 \\ \tilde{\theta}(X, Y), & \text{if } y_1 < y_2 \end{cases}$$

For all $p \in L^2$, the orbit of $p = (p_1, p_2)$ under θ' is

$$(L_1^1)_{(p)} = \begin{cases} L_r^1, & p_1 \geq p_2 \\ \tilde{L}_r^1, & p_1 < p_2 \end{cases}.$$

Also, for all $g \in L^2$ the mappings $\theta'_g : L^2 \longrightarrow L^2$ defined by

$$\theta'_g(X) = \theta'(g, X)$$

are diffeomorphisms.

Theorem 5. The mappings θ'_g are isometrics of L^2 .

Proof. Let $X = (x_1, x_2)$, $Y = (y_1, y_2) \in L^2$ and $g = (g_1, g_2) \in L_1^1$. Thus

$$d_L(\theta'_g(X), \theta'_g(Y))^2 = d_L[(\langle g, X \rangle, \langle g, X_S \rangle), (\langle g, Y \rangle, \langle g, Y_S \rangle)]^2$$

$$\begin{aligned}
&= (\langle g, X \rangle - \langle g, Y \rangle)^2 - (\langle g, X_S \rangle, \langle g, Y_S \rangle)^2 \\
&= \langle g, X - Y \rangle^2 - \langle g, X_S - Y_S \rangle^2 \\
&= (g_1(x_1 - y_1) + g_2(x_2 - y_2))^2 - (g_1(x_2 - y_2) + g_2(x_1 - y_1))^2 \\
&= g_1^2(x_1 - y_1)^2 + g_2^2(x_2 - y_2)^2 + 2g_1g_2(x_1 - y_1)(x_2 - y_2) \\
&\quad - g_1^2(x_2 - y_2)^2 - g_2^2(x_1 - y_1)^2 - 2g_1g_2(x_2 - y_2)(x_1 - y_1) \\
&= (g_1^2 - g_2^2)(x_1 - y_1)^2 - (g_1^2 - g_2^2)(x_2 - y_2)^2 \\
&= (x_1 - y_1)^2 - (x_2 - y_2)^2 \\
&= d_L(X, Y)^2
\end{aligned}$$

where $x_1 < x_2$, $y_1 < y_2$. All other possibilities, which are $x_1 \geq x_2$, $y_1 < y_2$ or $x_1 \geq x_2$, $y_1 \geq y_2$ or $x_1 < x_2$, $y_1 \geq y_2$ can be verified as above.

REFERENCES

- [1] Brickel, F., Clark, R.S., *Differentiable Manifolds*, 1970, New York: Van Nostrand.
- [2] Dubrovin, B.A., Fomenko, A.T., Novikov, S.P., *Modern Geometry Methods and Applications*, 1992, New York: Springer-Verlag.
- [3] Gündoğan, H. The cylinder Lie group in E^5 and its action as Lie transformation group, *Algebras, Groups and Geometries* 14 (1997), 453-459.
- [4] O'Neill, B., *Semi-Riemann Geometry with Application to Relativity*, 1983, New York: Academic Press.